

Design and Fabrication of a Simple Device for Folding Towel

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Abstract

Electronic technology makes work more manageable, and various electronic gadgets have been invented to assist humans. One of the most time-consuming activities is household chores, such as laundry. Daily laundry tasks are easier to manage with the help of washing and drying machines. However, the folding task is still done by hand and is not automated. A towel is one of the main clothes in daily life. Commonly, people use bare hands to fold the towel. However, this task consumes much time and energy; consequently, boredom, tiredness, and fatigue occur. The existing device to fold towels usually has a large physical compartment and is mainly used for industrial purposes, such as at hotels or laundry shops. The towel-folding machine is in increasing demand in our daily lives. Therefore, this project was developed and designed to eliminate the tedious folding of towels. The main aim is to design and develop an effective mechanism for folding rectangular towels using electronic components. The other objective is to compare the timing of folding rectangular towels using a simple device and by hand. As a result, the prototype represented a semi-automation system that incorporates mechanical and electronic designs. The prototype assembly with a folding board made from polypropylene plastic. The amount of time to fold one towel using a semi-automatic folding board remains the same throughout the process, while the amount of time required to fold towels by hand increases. In conclusion, a prototype was designed and developed successfully with various electronic components: HC-SR04 ultrasonic sensor, MG996R servomotor and Arduino. Besides, by comparing the timing of folding rectangular towels using a simple device and by hand, 94 seconds was reduced when folding 50 sheets with the aid of the device, compared to by hands. In other words, the effectiveness of the device is 20%.

Keywords: Folding, towel, ultrasonic sensor, servomotors, Arduino.

1. Introduction

Science and technology are advancing quickly, playing an important role in human progress. Electronic technology is one way to make human work more manageable. According to Miller et al. (2011), various useful and efficient electronic gadgets were invented to assist humans in meeting their needs. Various humanly operated equipment are gradually being abandoned instead of fully automatic equipment, resulting in automated equipment dominating human existence. One of the most time-consuming activities is the housewife's household chores. This activity is carried out every day, and Osawa et al. (2006), found that it is not complete when home chores are neglected. Daily laundry tasks, one of the house chores, are easier to manage with the help of washing machines and dryers. However, the folding task is still done by hand and is not automated.

Folding dried garments is one of the domestic duties that is a worry for this topic. Doumanoglou et al. (2016) researched how when there are many garments; it takes a long time to fold and tidy up the clothes swiftly and neatly, wasting time for other activities. According to Kido & Takahashi (2019), most people fold their clothing by hand. A towel is one of the main clothes in our daily life. Commonly, people use their bare hands to fold the towel. However, this task consumes much time and energy; consequently, boredom, tiredness and fatigue occur. The existing device to fold towels usually has a large physical compartment. They are mainly used for industrial purposes, such as at hotels or laundry shops.

The towel-folding machine is in increasing demand in our daily lives. Therefore, this project was developed and designed to eliminate the tedious folding of towels. The main aim is to design and develop an effective mechanism for folding rectangular towels using a few electronic components. The second objective is to compare the timing of folding rectangular towels using a simple device and by hand. In summary, this research paper is about improving the towel-folding tool to provide improved features such as reducing folding time, saving physical energy while folding many towels, and overcoming challenges in handling the device if it is complicated.

2. Literature Review

The folding of towels will be classified into two types in this project based on technology. The manual folding, done by hand, is the first step. It is the most ancient method today. The second type is the semi-automated method, in which

the garments are set out on a platform and subsequently folded by the machine. This two-type folding towel was undergoing extensive investigation because no complete breakthrough has been realised in this area.

The folding board, also known as the flip fold, comprises four rectangular pieces: two long rectangular boards and two small rectangular boards that fold the towel into a perfect rectangle. Only the upper middle section of the board is connected to the rest. Towels are folded by flipping the different parts of the board in a primary sequence. Mostly, the board's material is made of Polypropylene resin. This lightweight and easy-to-handle fabric folder were suitable for this innovation.

Servomotors are automatic devices with a rotary turning angle of 360 degrees according to the setup, mostly connected to the Arduino Uno. It can rotate or push parts of the board with precision. Servos are primarily used to control angular or linear position, velocity, and acceleration. The input voltage varies depending on the size and torque output of the servo; however, most servos will operate nicely with 5V from a microcontroller or battery circuit. The current draw a servo can pull while moving and with a load attached is more essential than voltage. When unloaded, a typical hobby servo can draw as little as 10mA, but larger servos under load can draw up to an Ampere or more. It is crucial to ensure that the power supply has the appropriate voltage range and generates enough current to move the servo with the towel attached to the board.

One form of energy can be transformed into another by using a sensor, which is a device that detects and then responds to various types of physical world input. Ultrasonic sensors use ultrasonic waves to measure distance. The sensor head produces an ultrasonic signal and receives a signal to detect the target. When using ultrasonic sensors, the distance to a target is determined by determining how long it takes the sensor to emit and receive the signal. Emission and reception are accomplished with the help of a single ultrasonic element. A single oscillator transmits and receives ultrasonic waves in a reflecting model ultrasonic sensor. This sensor will detect a towel approaching the mainboard and give Arduino input to operate the device. Table 1 shows a summary literature review on the servomotor and ultrasonic sensors.

Table 1: Summary of literature review on the servomotor and ultrasonic sensor

No.	Author (Year)	Title	Objective	Method	Result / Findings
1.	Sadun et al. (2015)	A Comparative Study on the Position Control Method of DC Servomotor with Position Feedback by using Arduino	A servo motor is an actuator that can be accurately regulated in terms of rotary and angular position.	Arduino IDE was used to code servomotor control.	Any closed-loop electrical system can use a positional rotation servo. Advantages include accurate angular position adjustment and real-time position feedback. Built-in potentiometer voltage feedback indicates the motor's exact angular location.
2.	Irawan et al. (2021)	Folding Clothes Tool Using Arduino Uno Microcontroller and Gear Servo	To design a model for clothes folding devices based on Arduino Uno and Gear Servo.	The microcontroller was designed with a servomotor as a clothes-folding medium. There was hardware programming.	After testing, the author concluded that clothes folding devices in the form of a microcontroller with a servo drive could be assembled with 3 to 6 servos, depending on clothing size. Because there are only three servos and they can only bear a small load, add six servos, one on each side of the current servo placement.
3.	Arun et al. (2020)	Object detection using ultrasonic sensor	The time it takes for ultrasonic waves to spread out and measure the distance they travel from the system to the target and return.	Arduino has a "Wiring" library. It generates many sophisticated input/output functions.	When an object is detected, its existence, angle, and distance are presented. This project can ensure human safety by detecting object interference at a specific distance. Finally, the project's goal has been reached without a hitch.
4.	Latha et al. (2016)	Distance Sensing with Ultrasonic Sensor and Arduino	To create and test an ultrasonic distance meter. The gadget presented here can detect the target and calculate its distance.	The most common method is the time of flight (ToF). ToF measures the time between an ultrasonic pulse train's emission and arrival after reflection. This slows single-measurement reaction times.	The device accurately measures distance. It measures distance without touching anything. The device is versatile. It's used in car backing systems, automation and robotics, snow depth, tank water level, and manufacturing line detection.

Based on the findings in Table 1, an MG996R would be used in this study since it is a servomotor with a maximum stall torque of 11 kg/cm and metal gears. The motor rotates from 0 to 180 degrees based on the duty cycle of the PWM wave given to its signal pin, just as other RC servos. Besides, an HC-SR04 ultrasonic sensor would be used since it sends out sound waves at a frequency of 40 kilohertz, which move through the air and detect the presence of any obstacles or objects in their path.

An Arduino is a circuit board programmed to do various tasks today, where programming is commonly utilised. An Arduino can read and send information from multiple sensors, antennas, and coding devices. It can also output data to various devices, such as LCD screens and stereo speakers. It sends data from a computer program to the microcontroller, executing a specific command. Software (The Arduino IDE) that input the information on command and hardware (Arduino Uno circuit board) that have many components to make it work are used together to programme the device.

3. Methodology

Figure 1 shows the process and development throughout the fabrication of semi-automatic folding towel parts in the flow chart form.

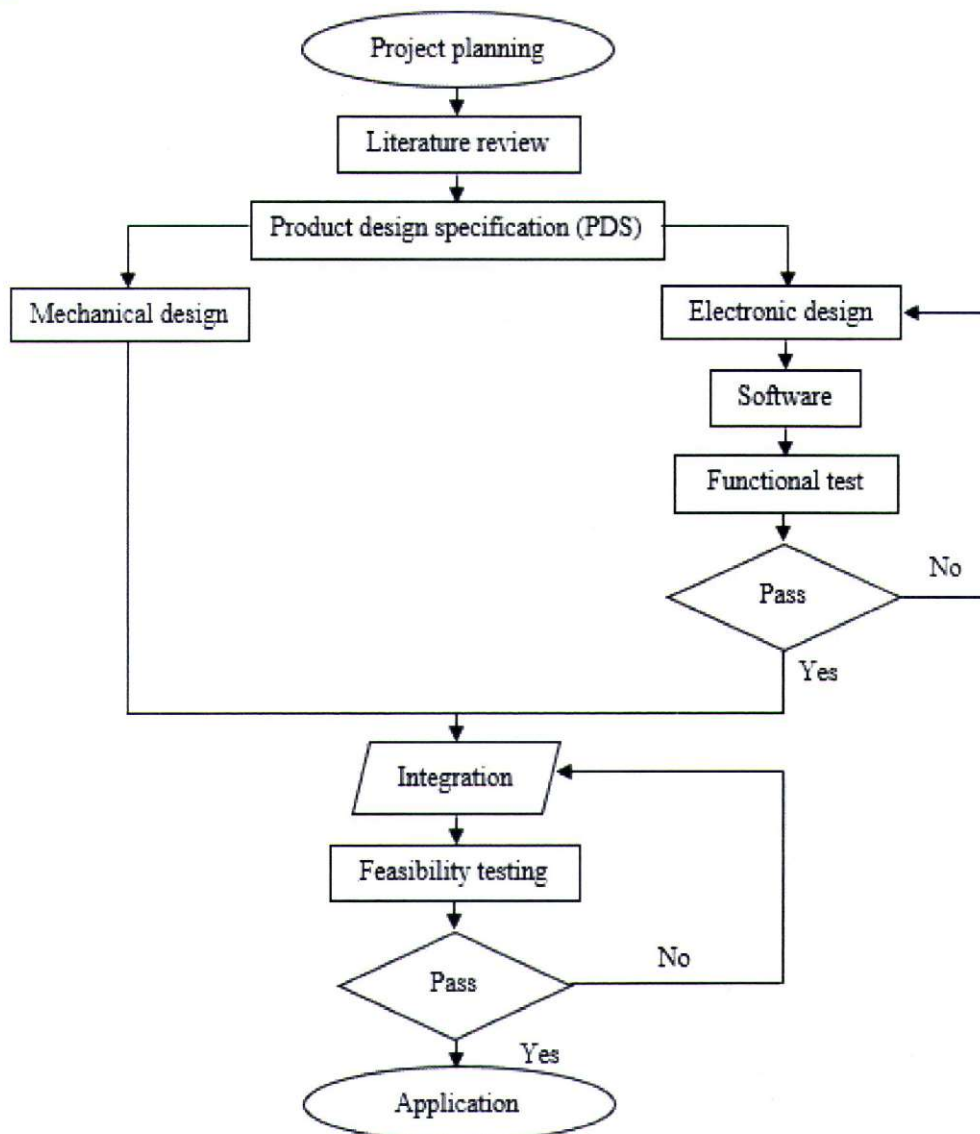


Figure 1: Flowchart for design and fabrication of part for a folding device

This project's background study is based on the folding board, servomotor, ultrasonic sensor, and Arduino literature review. Product Design Specifications (PDS) were built based on the customer requirements and used for conceptual design generation. Mechanical design, including the few designs concept, concept evaluation, weight decision matrix, technical drawing and fabrication. Electronic design, including coding in the software and electronic functional testing. Lastly, feasibility testing was done to determine whether or not the prototype could operate properly.

3.1. Potential Difficulties and Challenges of the Product

The product was expected to encounter specific difficulties while used for folding purposes. As a result, four presumptive difficulties were identified, and a recommended method for resolving them was. Table 2 shows potential difficulties and challenges for a folding towel device.

Table 2: Potential difficulties and challenges for a folding towel device.

Challenges / Difficulties	Effect on product	Proposed solution
Less durable power supply	Fewer towels cannot be fold	Using direct current or using a battery with a large mAh capacity
Electronic compartment functionality	<ul style="list-style-type: none"> • The ultrasonic sensor does not detect towels that are placed on board. • The servo is stuck and unable to move the board. 	<ul style="list-style-type: none"> • Place the ultrasonic sensor in a place that makes it easy to detect the towel. • Choose a servo with high durability and powerful.
Material of the board	<ul style="list-style-type: none"> • Heavy to lift it. • Towel slips from the board. 	Using light material with a rough surface, such as plastic or polypropylene resin
Coding	Wrong instructions given on the Arduino will affect the process of the folding	Try and error on coding to manage the proper process of folding towels neatly

3.2. Product Design Specification (PDS)

A product design specification, as shown in Table 3, is a product requirement. It provides all the product information with specific features and functionalities and offers a technical description, performance specification, technical standards to meet, and other details. The project design specification is based on the general requirement.

Table 3: Product design specification (PDS)

General Requirement	Specific Requirement	Acceptance Performance
Automatic	Auto-fold the towel	<ul style="list-style-type: none"> • Using Arduino to generate the folding board. • Servo to move and fold the towel.
Safety	No harm to the user	<ul style="list-style-type: none"> • No sharp edge on the product. • All electronic compartments will be covered.
Quality	<ul style="list-style-type: none"> • Fold in a nice shape. • Easy to use. • Lifespan. • Lightweight and durable material. 	<ul style="list-style-type: none"> • Neat fold shape. • Place a towel on the product, and it will fold automatically. • Long-lasting. • Not easy to break.
Dimension	<ul style="list-style-type: none"> • Portable and easy to carry. • Easy to move. • Easy to store. 	<ul style="list-style-type: none"> • Length: 58 cm. • Width: Fold = 24cm, Unfold = 72 cm. • Height: 7 cm.
Reduce time	<ul style="list-style-type: none"> • Shorter time to fold with a neat shape. • Simple installation process. 	< 1 min

3.3. Conceptual Design

Design concept generation entails creating many goods to investigate product design specifications. This procedure begins with client criteria and concludes with several concept design possibilities to select a final design. Several concept hand sketching was drawn on A4 paper. In this project, four designs were created and compared to find the most satisfactory product. Figure 2 shows four sketches of four concepts for a folding device.

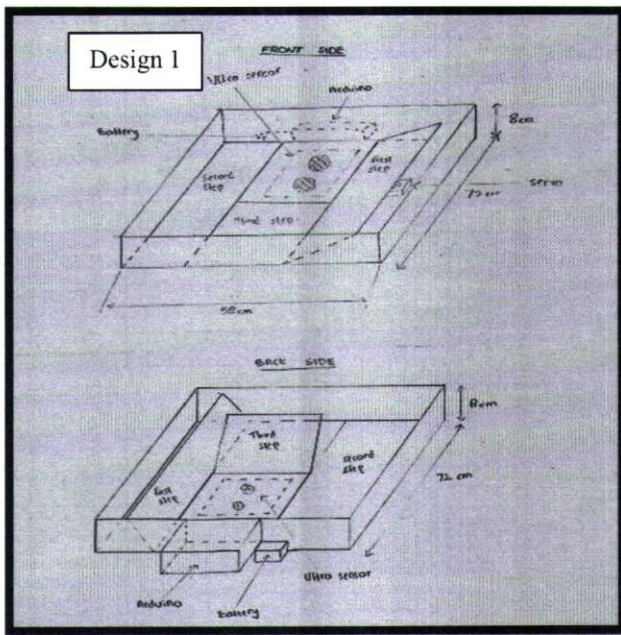
Based on Figure 2(a), this sketch provides the simplest design that fulfils the folding towel requirement. With human power to put the towel on the mainboard, the ultrasonic sensor commands the Arduino and moves the other board to fold the towel. The board and all electronic parts are secure in the box to avoid breaking easily. Besides, design concept 2 (Figure 2(b)) has a folding board on top that support more towel size, and other electronic parts are secure under the box. The ultrasonic sensor will instruct the Arduino to move the other board to fold the towel. The board and all electronic components are safely enclosed in a box to prevent accidental damage.

Design concept 3 differs from other designs, as shown in Figure 2(c). The ultrasonic sensor will instruct the Arduino to move the other board to fold the towel. The uniqueness of this design is the existence of a slide. After the towel has been folded, it will slide into the basket. Every component is electronically stored in the body to avoid any damage. The design looks safer based on design concept 4 (Figure 2(d)) because the system is located in a box made from quality stainless steel. The system cannot be seen in this design since every electronic component and board are in the box.

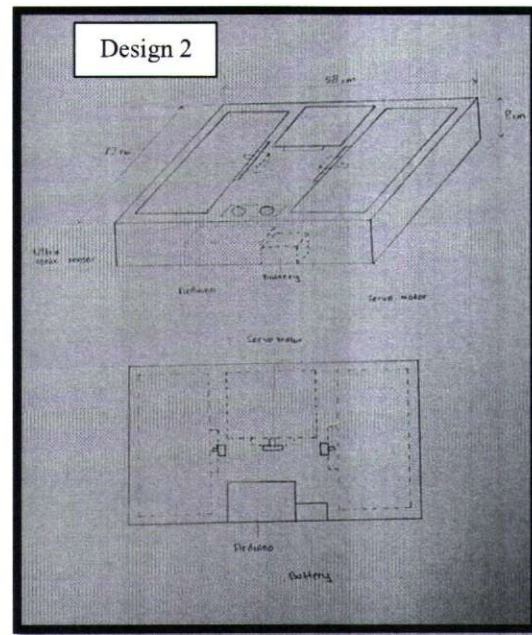
Therefore, the consumer only needs to put the towel in the box. As a result, the Arduino will tell the second board to fold a towel using an ultrasonic sensor. Finally, the consumer takes the towel from the output port.

3.4. Concept Evaluation

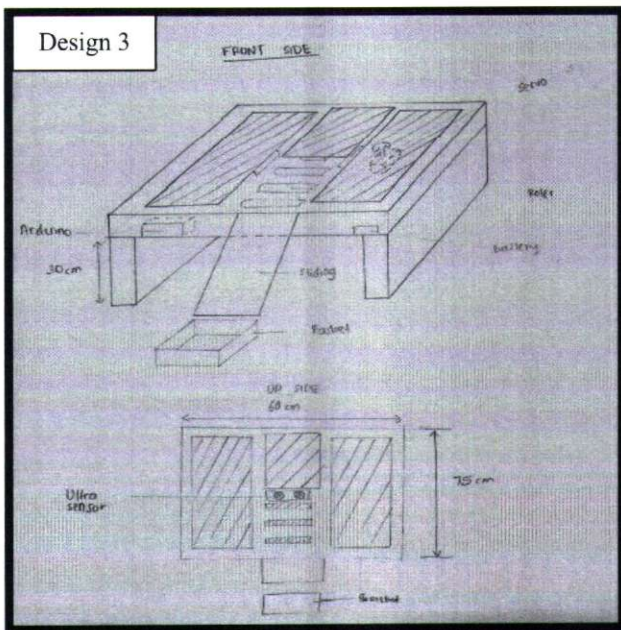
All four design concepts were analysed and screened to develop a final design concept. Each design concept was run through the Pugh design concept selection table in the first step. Based on comparing the current folding device with the product design specification, some features were identified, and scores were given, as shown in Table 4. A score of (-) is given to the designs that do not satisfy the criteria by the potential user, while (+) is given to the designs that meet advanced standards, and (0) is allocated to the designs that follow the reference. Add all of the (0), (+), and (-) to get a net score for each design concept. The top two design ideas with the highest net score will move on to the next phase of the screening.



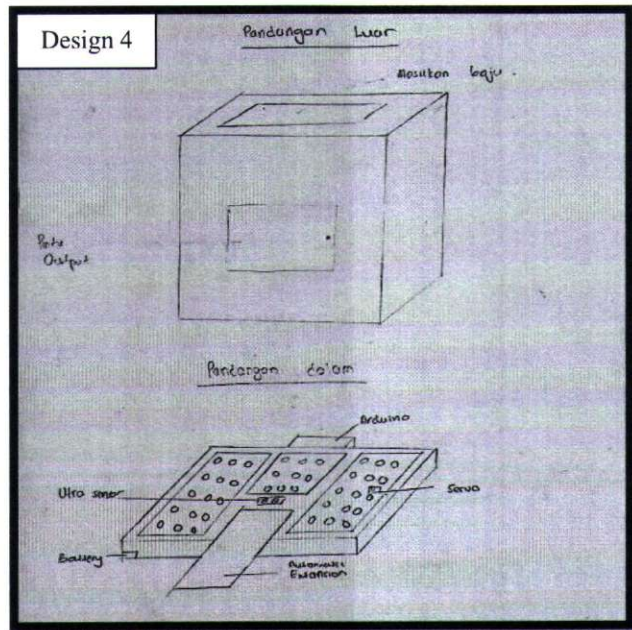
(a) Design 1



(b) Design 2



(c) Design 3



(d) Design 3

Figure 2: Sketch of four concepts for a folding device.

Table 4: Pugh design concept selection for 4 designs.

Features	Design Concept Variation				Reference
	Design 1	Design 2	Design 3	Design 4	
Effectiveness of Mechanism	0	0	0	0	0
Capacity	-	+	+	+	0
Safety	+	+	+	-	0
Weight	+	+	-	-	0
Cost	0	0	-	-	0
Maintenance	0	0	0	0	0
Storage Space	+	+	-	-	0
Plus	3	4	2	1	
Same	3	3	2	2	
Minus	1	0	3	4	
Nett	2	4	-1	-3	
Rank	2	1	3	4	
Continue ?	YES	YES	NO	NO	

3.5. Weight Decision Matrix

The two design concepts that made it past the first stage of screening will be subjected to the second stage to determine which will be produced in this project. The design ideas that passed the previous screening are Design 1 and Design 2. In the next screening exam, a weighted choice matrix will be used. Each design concept will be given points based on the selection criteria. Prior to that, a score of 1 to 5 will be assigned to each of the seven qualities used in the selection criterion. All of these categories will be defined, as shown in Table 5. Each unique design concept will be given a rating, awarding a score to the design ideas. Each criterion will be awarded 100% based on its importance. The rate allocated to each of the seven design ideas will compound this percentage weighting.

Table 5: Weight Decision Matrix for two designs

Criteria	Weight(%)	Concepts			
		Design 1		Design 2	
		Rating	Weightage score	Rating	Weightage score
Safety	20%	3	0.6	5	1
Capacity	15%	3	0.45	4	0.6
Effectiveness of Mechanism	15%	5	0.75	5	0.75
Maintenance	15%	5	0.75	5	0.75
Cost	15%	4	0.6	4	0.6
Weight	10%	5	0.4	3	0.3
Storage Space	10%	4	0.5	5	0.5
Total score		29	4.05	31	4.5
Ranking		2		1	
Continue ?		NO		YES	

3.6. Materials.

The fabricated parts, acrylic plates, were chosen and cut using a cutting machine according to the dimensions in the drawing. The acrylic plates were put together with acrylic glue and hot glue. Hinges and locks were used too. Referring to the previous literature review, a folding board; besides the HC-SR04 ultrasonic sensor; MG996R servo motor, and Arduino Uno R3, were used as electronics parts.

4. Results and Discussion

The folding towel device may be described as a semi-automatic device that an Arduino controls as the brain and other electronic components, such as an ultrasonic sensor, servo motors, and a battery for power. Before moving on to the following procedure, this technology requires human physical energy to place the towel on the board. The first question is whether the servo is powerful enough to move the board when loaded with a towel. Next, if the ultrasonic sensor fails to detect the presence of towels on the board, the entire system will fail to work. The last point to consider is how adaptable the equipment is to folding many towels at once. In order to save energy and time, it is hugely beneficial if the device can withstand several folds without difficulty. Figure 3 shows the full assembly of a semi-automatic folding device.

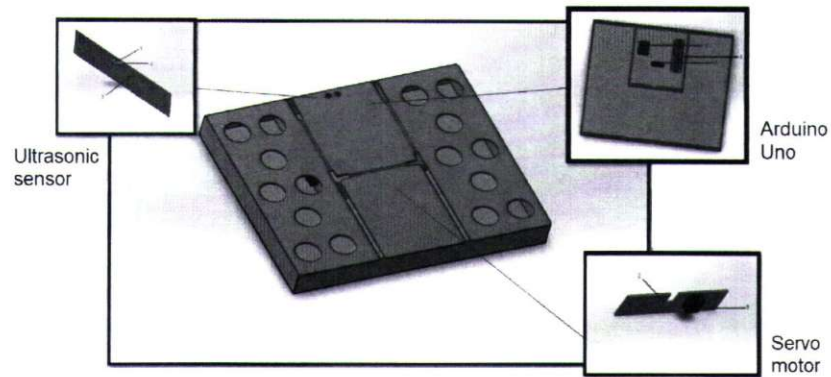


Figure 3: Full assembly of a semi-automatic folding device

The prototype for this project was developed by putting together all the parts. Figure 4 shows the prototype assembly with a folding board made from polypropylene plastic. Figure 5 shows the step of the semi-automatic folding device function. Objective 2 is to compare the timing between using the semi-automatic folding device and folding using a bare hand. Usually, folding towels in small quantities will be easier and faster when folded by hand, but the result of folding depends on one's tidiness. However, folding towels in large quantities will cause tiredness and fatigue to the folders, and the result will be less neat.

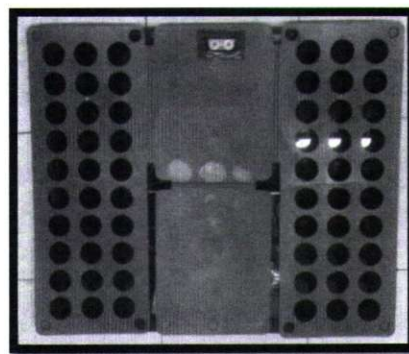


Figure 4: Full assembly of the prototype

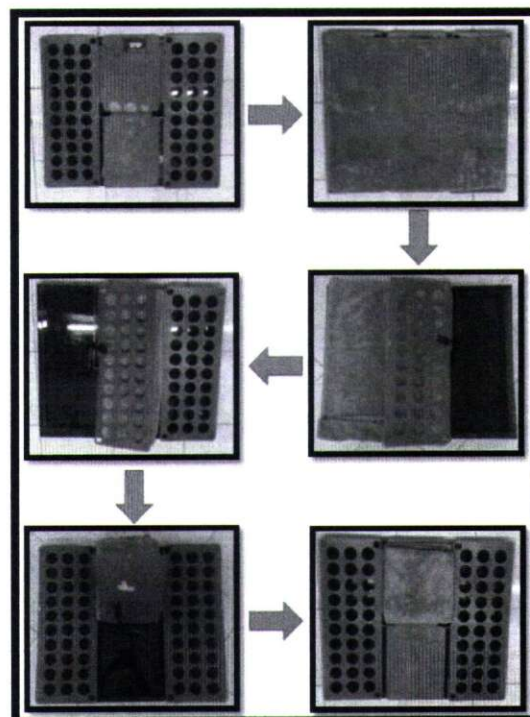


Figure 5: The process of folding towel

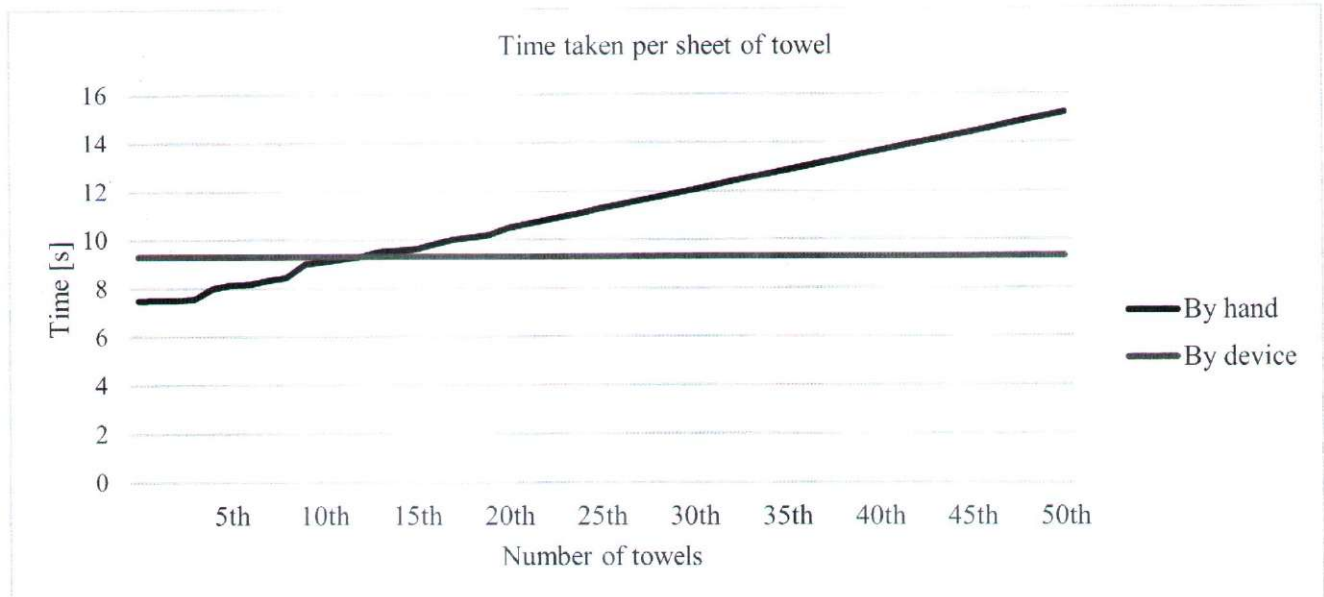


Figure 6: Time comparison between by hand and a semi-automatic device.

Figure 6 shows the time to fold each towel from the first sheet to the 50th sheet, using bare hands and a semi-automatic device. The amount of time to fold one towel using a semi-automatic folding board remains the same throughout the process, while the amount of time required to fold towels by hand increases due to human factors such as boredom, tiredness, and fatigue. 94 seconds was reduced when folding 50 sheets with the aid of the device, compared to by hands. In other words, the effectiveness of the device is 20%.

5. Conclusion

People often want to simplify daily affairs to save time and energy so that more other matters can be done. Much research has been done to make things easier and create an atmosphere where people take easy steps to complete their tasks. In this project, the device represented a semi-automation system that incorporates mechanical and electronic control designs. In conclusion, a prototype was designed and developed successfully with various electronic components: HC-SR04 ultrasonic sensor, MG996R servomotor and Arduino. Besides, by comparing the timing of folding rectangular towels using a simple device and by hand, 94 seconds was reduced when folding 50 sheets with the aid of the device, compared to by hands. In other words, the effectiveness of the device is 20%. As a recommendation for improvement, the electronic component should be replaced with a faster mechanism component. Besides, the product functionality is suggested to fold other garments of various shapes and types.

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